Visit <u>this link</u> to read the introductory text for this syllabus.

AREAS COMMON TO THE TWO ALTERNATIVES		ADDITIONAL TO FOR ALTERN		
			ALTERNATIVE X	ALTERNATIVE Y
ТОРІС	CONTENT	NOTES	(For Candidates offering Further Maths)	(For Candidates offering Maths Elective)
Circular Measure and Radians	Lengths of Arcs of circles Perimeters of Sectors and Segments measure in radians			
2. Trigonometry	(i) Sine, Cosine and Tangent of angles	For $O^0 \le \theta \le 360^0$		
	(ii) Trigonometric ratios of the angles 30^0 , 45^0 , 60^0	Identify without use of tables.		
	(iii) Heights and distances			
WW'	(iv) Angles of elevation and depression(v) Bearings, Positive and negative angles.	Simple cases only.	U.C	om
	(vi) Compound and multiple angles.	Their use in simple Identities and solution of trig. ratios.		
	(vii) Graphical solution of simple trig. equation.	$a\cos x + b\sin x = c$		
	(viii) Solution of triangles.	Include the notion of radian and trigonometric ratios of negative angles.		
3. Indices, Logarithms		_		
and Surds. (a) Indices	(i) Elementary theory of Indices.	Meaning of a^0 , a^{-n} , a^n		
(b) Logarithms	(ii) Elementary theory of Logarithm	Calculations involving multiplication, division, power and nth		
	$\log_a xy = \log_a x + \log_a y,$	roots:		
	$\log_a x_n = n\log_a x$	$\log a^n, \log \sqrt{a}, \log a^{\frac{n}{n}}$		
	(iii) Applications	Reduction of a relation		

such as $y = ax^b$, (a, b) are constants to a linear form.

 $\log_{10} y = b \log_{10} x + \log_{10} a$. Consider other examples such as $y = ab^x$.

AREAS COMMON TO THE TWO ALTERNATIVES		ADDITIONAL TOPICS /NOTES FOR ALTERNATIVES		
ТОРІС	CONTENT	NOTES	ALTERNATIVE X (For Candidates offering Further Maths)	ALTERNATIVE Y (For Candidates offering Maths Elective)
(c) Surds	Surds of the form $ \underline{a}, a\sqrt{a} \text{ and } a+b\sqrt{n} $ where a is rational. $b \text{ is a positive integer and } n \text{ is } not \ a \text{ perfect square.}$	Rationalisation of the Denominator: $ \frac{a + \sqrt{b}}{\sqrt{c} - \sqrt{d}} $,
(d) Sequences: Linear and Exponential sequences	 (i) Finite and infinite sequences (ii) U_n = U₁ + (n - 1) d, where <i>d</i> is the common difference. 			
WW	(iii) $S_n = \frac{n}{2} (U_1 + U_n)$ (iv) $U_n = U_1 r^{n-1}$ where r is the common ratio. (v) $S_n = U_1(1-r^n)$; $r < 1$	ned	U.C	om
(e) Use of the Binomial Theorem for a positive integral index.	or $S_n = \underline{U_1} \frac{(r^n - 1)}{r - 1}; r > 1$ Proof of Binomial Theorem not required. Expansion of $(a + b)^n$ Use of $(1 + x)^n \approx 1 + nx$ for any rational n , where x is sufficiently small e.g. $0(0.998)^{\frac{7}{3}}$			
4. Algebraic Equations	 (a) Factors and Factorisation. Solution of Quadratic equations using:- (i) completing the square, (ii) formula. (a) Symmetric properties of the equation ax² + bx + c = 0 	The condition $b^2 - 4ac \ge 0$ for the equation to have real roots. Sum and product of roots.		
	(b) Solution of two simultaneous equations where one	Graphical and analytical		

is linear and the other quadratic.

methods permissible.

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AREAS COMMON TO THE TWO ALTERNATIVES		ADDITIONAL TO FOR ALTERN		
ТОРІС	CONTENT	NOTES	ALTERNATIVE X (For Candidates offering Further Maths)	ALTERNATIVE Y (For Candidates offering Maths Elective)
6. Rational Functions and Partial Fractions	 (i) Addition, subtraction and multiplication of polynomials. (ii) Factor and remainder theorems (iii) Zeros of a polynomial function. (iv) Graphs of Polynomial functions of degree n ≤ 3. (v)Division of a polynomial of degree not greater than 4 by a Polynomial of lower degree. e.g. f: x → px² + qx + r (i) The four basic operations. (ii) Zeros, domain and range; Sketching not required. 	Not exceeding degree 4	(iii) Resolution of rational functions into partial fractions. Rational functions of the form $Q(x) = \frac{F(x)}{G(x)}$ $G(x) \neq 0$ where $G(x)$ and $F(x)$ are polynomials, $G(x)$ must be factorisable into linear and quadratic factors (Degree of Numerator less than that	

of denominator which is less than or equal to 4)

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ТОРІС	CONTENT	NOTES	ALTERNATIVE X (For Candidates offering Further Maths)	ALTERNATIVE Y (For Candidates offering Maths Elective)
7. Linear Inequalities	Graphical and Analytical Solution of simultaneous linear Inequalities in 2 variables and Quadratic inequalities.			
8. Logic	(i) The truth table, using not P or Q , P and Q . P implies Q , Q implies P .	Validity of compound statements involving implications and connectives.		
	(ii) Rule of syntax: true or false statements, rule of logic applied to arguments, implications and deductions	Include the use of symbols: $\sim P$ $p \vee q, p \wedge q, p \Rightarrow q$ Use of Truth tables.		
9. Co-ordinate Geometry: Straight line	(a) (i) Distance between two points; (ii) Mid-point of a line segment;	ned	U.C	om
	(iii) Gradient of a line;(iv) Conditions for parallel and perpendicular lines.	Gradient of a line as ratio of vertical change and horizontal change.		
	(b) Equation of a line:(i) Intercept form;(ii) Gradient form;(iii) The general form.			
Conic Sections	(c) (i) Equation of a circle; (ii) Tangents and normals are required for circle.	 (i) Equation in terms of centre and radius e.g. (x-a)² + (y-b)² = r²; (ii) The general form: x² + y² + 2gx + 2fy + c = 0; 	(iii) Equations of parabola in rectangular Cartesian coordinates.	
10. Differentiation	(a) (i) The idea of a limit	(i) Intuitive treatment of limit. Relate to the		

AREAS COMMON TO THE TWO ALTERNATIVES		ADDITIONAL TOPICS /NOTES FOR ALTERNATIVES		
ТОРІС	CONTENT	NOTES	ALTERNATIVE X (For Candidates offering Further Maths)	ALTERNATIVE Y (For Candidates offering Maths Elective)
	(ii) The derivative of a function. Application of differentiation Quotier (b) (i) Second derivatives and Rates of change; (ii) Concept of maxima and minima.	 (ii) Its meaning and its determination from first principles in simple cases only. e.g. axⁿ + b, n ≤ 3, (n ∈ I) (iii) Differentiation of polynomials e.g. 2x⁴ - 4x³ + 3x² - x + 7 and (a + bxⁿ)^m trules. (i) The equation of a tangent to a curve at a point. (ii) Restrict turning points to maxima and minima. (iii) Include curve sketching (up to cubic functions) and linear kinematics. 	(iv) Product and Differentiation of implicit functions such as $ax^2 + by^2 = c$	OM
11. Integration	(i) Indefinite Integral	 (i) Exclude n = -1 in ∫xⁿdx. (ii) Integration of sum and difference of polynomials e.g. 4 x³ + 3x² - 6x + 5 include linear kinematics. Relate to the area under a curve. 		

AREAS COMMON TO THE TWO ALTERNATIVES		ADDITIONAL TOPICS /NOTES FOR ALTERNATIVES		
TOPIC	CONTENT	NOTES	ALTERNATIVE X (For Candidates offering Further Maths)	ALTERNATIVE Y (For Candidates offering Maths Elective)
	(iii) Applications of the definite integral	(iii) Plane areas and Rate of change.		(iii) Volume of solid of revolution. (iv) Approximation restricted to trapezium rule.
12. Sets	 (i) Idea of a set defined by a property. Set notations and their meanings. (ii) Disjoint sets, Universal set and Complement of set. 	$\{x: x \text{ is real}\}, \ \cup, \cap$ empty set $\{\ \}, \ \emptyset, \ \in, \notin, C,$ U (universal set) or $\{\ \}$ A (Complement of set A).		
WW'	 (iii) Venn diagrams, use of sets and Venn diagrams to solve problems. (iv) Commutative and Associative laws, Distributive properties over union and intersection 	ned	U.C	om
13. Mappings and Functions		The notation: e.g. $f: x \rightarrow 3x + 4$ $g: x \rightarrow x^2$ where $x \in R$.		
	(i) Domain and co-domain of a function.	Graphical representation of a function.		
	(ii) One-to-one, onto, identity and constant mapping;	Image and the range.		
	(iii) Inverse of a function;			
	(iv) Composition of functions.	Notation: fog $(x) = f(g(x))$ Restrict to simple algebraic functions only.		

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TOPIC	CONTENT	NOTES	ALTERNATIVE X (For Candidates offering Further Maths)	ALTERNATIVE Y (For Candidates offering Maths Elective)
14. Matrices: (a) Algebra of Matrices. (b) Linear Transformation	 (i) Matrix representation (ii) Equal matrices (iii) Addition of matrices (iv) Multiplication of a Matrix by a scalar. (v) Multiplication of matrices. 	Restrict to 2 x 2 matrices Introduce the notation A, B, C for a matrix. (i) The notation I for the unit identity matrix. (ii) Zero or null matrix.	U.C	Some special matrices: (i) Reflection in the x-axis; Reflection in the y-axis. The clockwise and anti-clockwise rotation about the origin. (ii) Inverse of a 2 x 2 matrix; (i) Restrict to the Cartesian plane; (ii) Composition of linear transformation; (iii) Inverse of a linear transformation; (iv) Some special linear transformations: Identity Transformation, Reflection in the x-axis Reflection in the y-axis; Reflection in the line y = x Clockwise and anti-clockwise rotation about the origin.

AREAS COMMON TO THE TWO ALTERNATIVES			ADDITIONAL TOPICS /NOTES FOR ALTERNATIVES	
ТОРІС	CONTENT	NOTES	ALTERNATIVE X (For Candidates offering Further Maths)	ALTERNATIVE Y (For Candidates offering Maths Elective)
(c) Determinants 15. Operations	Binary Operations: Closure, Commutativity, Associativity and Distributivity, Identity elements and inverses.	ned	Evaluation of determinants of 2 x 2 and 3 x 3 matrices. Application of determinants to: (i) Areas of triangles and quadrilaterals. (ii) Solution of 3 simultaneous linear equations	O M

PART II STATISTICS AND PROBABILITY

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AREAS CO	OMMON TO THE TWO ALT	ERNATIVES	ADDITIONAL TO FOR ALTERN	
			ALTERNATIVE X	ALTERNATIVE Y
ТОРІС	CONTENT	NOTES	(For Candidates offering Further Maths)	(For Candidates offering Maths Elective)
 Graphical representation of data Measures of location 	(i) Frequency tables. (ii) Cumulative frequency tables. (iii) Histogram (including unequal class intervals) (iv) Frequency curves and ogives for grouped data of equal and unequal class intervals. Central tendency; Mean, median, mode, quartiles and percentiles	Include: (i) Mode and modal group for grouped data from a histogram; (ii) Median from grouped data and from ogives; (iii) Mean for grouped data, use of an assumed mean required.	U.C	OM
3. Measures of Dispersion	 (a) Determination of: (i) Range, Inter-Quartile range from an ogive. (ii) Variance and standard deviation. 	Simple applications. For grouped and ungrouped data using an assumed mean or true mean.		
4. Correlation	(i) Scatter diagrams	Meaning of correlation: positive, negative and zero correlations from scatter diagrams.	Rank correlation Spearman's Rank Correlation Coefficient. Use data without ties	

(ii) Line of fit

Use of line of best fit to predict one variable from another.

Meaning and applications.

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of probability requency of Probability. The sample spaces and multiplication of the sample spaces.	NOTES E.g. tossing 2 dice once, drawing balls from a box without replacement. Equally likely events and	ALTERNATIVE X (For Candidates offering Further Maths)	ALTERNATIVE Y (For Candidates offering Maths Elective)
of probability requency n of Probability. uple sample spaces. and multiplication of	E.g. tossing 2 dice once, drawing balls from a box without replacement. Equally likely events and	offering Further	offering Maths
equency n of Probability. ple sample spaces. nd multiplication of	drawing balls from a box without replacement. Equally likely events and		
	mutually exclusive events only to be used.	Probability Distribution.	
		Binomial Probability $P(x = r) = {}^{n}C_{r}p^{r}q^{n-r}$	
		where Probability of success = P	
.Lai	rned	Probability of failure $= q$, $p + q = 1$ and n is the number of trials. Simple problems only.	om
ses of number of nts on a line.	e.g. (i) arrangement of students in a row.		
	(ii) drawing balls from a box. Simple problems only.		
	${\rm P}_{\rm r} = \frac{\rm n!}{\rm (n-r)!}$		
	$^{n}C_{\Gamma} = \frac{n!}{r!(n-r)!}$		
	ses of combination	from a box. Simple problems only.	from a box. Simple problems only. $ P_{r} = \frac{n!}{(n-r)!} $ sees of combination $ P_{r} = \frac{n!}{(n-r)!} $

PART III VECTORS AND MECHANICS

AREAS COMMON TO THE TWO ALTERNATIVES			ADDITIONAL TO FOR ALTERN	
ТОРІС	CONTENT	NOTES	ALTERNATIVE X (For Candidates offering Further Maths)	ALTERNATIVE Y (For Candidates offering Maths Elective)
1. Vectors	(i) Definitions of scalar and vector quantities.			
WW	(iii) Representation of Vectors. (iii) Algebra of vectors.	(iii) Addition and subtraction of vectors, Multiplication of vector by vectors and by scalars. Equation of vectors.	U.C	om
	(iv) Commutative, Associative and Distributive properties.	(iv) Illustrate through diagram, diagrammatic representation. Illustrate by solving problems in elementary plane geometry e.g. concurrency of medians and diagonals.		
	(v) The parallelogram Law.	The notation		
	(vi) Unit Vectors.	i for the unit vector \[\begin{pmatrix} 1 \\ 0 \\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \		

along the *x* and *y* axis respectively.

(vii) Position and free Vectors.

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		TERNATIVES	FOR ALTERNATIVE X	NATIVES ALTERNATIVE Y
ТОРІС	CONTENT	NOTES	(For Candidates offering Further Maths)	(For Candidates offering Maths Elective)
	(viii) Resolution and Composition of Vectors.	(viii) Not more than three vectors need be composed.		
	(ix) Scalar (dot) product and its application.	Using the dot product to establish such trigonometric formulae as (i) $\cos(a \pm b) = \cos a$		
		$\cos b \pm \sin a \sin b$ (ii) $\sin (a \pm b) = \sin a$ $\cos b \pm \sin b \cos a$ (iii) $c^2 = a^2 + b^2 - 2ab \cos c$		
2. Statics	(i) Definition of a force.	Finding angle between two vectors.	lu.c	On
	(ii) Representation of Forces.			
	(iii) Composition and resolution of coplanar forces acting at a point.			
	(iv) Equilibrium of particles.	(iv) Apply to simple problems e.g. suspension of particles by strings.		
	(v) Lami's theorem	(v) Apply to simple problems on equivalent system of forces.		
	(vi) Determination of Resultant.		(vi) Composition and resolution of general coplanar forces on rigid bodies.	
			(viii) Moments of forces.	

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AREAS COMMON TO THE TWO ALTERNATIVES			ADDITIONAL TOPICS /NOTES FOR ALTERNATIVES	
ТОРІС	CONTENT	NOTES	ALTERNATIVE X (For Candidates offering Further Maths)	ALTERNATIVE Y (For Candidates offering Maths Elective)
				Friction: Distinction between smooth and rough planes. Determination of the coefficient of friction required.
3. Dynamics	(a) (i) The concepts of Motion, Time and Space. (ii) The definitions of displacement, velocity, acceleration and speed. (iii) Composition of velocities and accelerations. (b) Equations of motion (i) Rectilinear motion; (ii) Newton's Law of motion. (iii) Consequences of Newton's Laws: The impulse and momentum equations: Conservation of Linear Momentum.	Application of the equations of motions: V = u + at; $S = ut + \frac{1}{2} at^2$; $V^2 = u^2 + 2as$.	U.C	OM
	(iv) Motion under gravity.		Motion along inclined planes.	

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